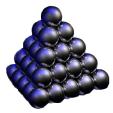
Moment methods in energy minimization

David de Laat

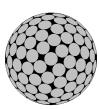
CWI Amsterdam

Andrejewski-Tage Moment problems in theoretical physics Konstanz, 9 April 2016

Packing and energy minimization



Sphere packing Kepler conjecture (1611)

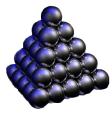




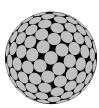
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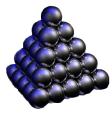


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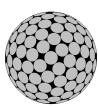
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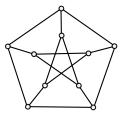


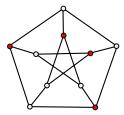


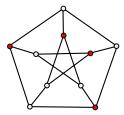
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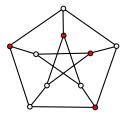




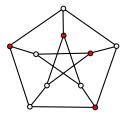


Example: the Petersen graph

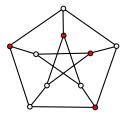
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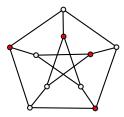
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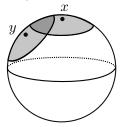
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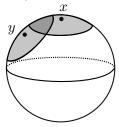
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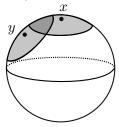


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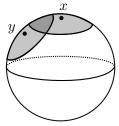
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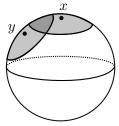
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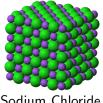


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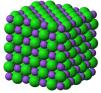


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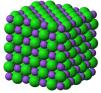
Sodium Chloride



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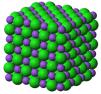


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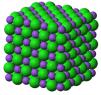
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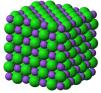
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- Positive semidefinite form $\langle f,g \rangle = A_t^* \lambda(f \otimes g)$ on $\mathcal{C}(I_t)$
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- If $\lambda \in \mathcal{M}(I_{2t})$ is of positive type and

$$\mathcal{C}(I_t) = \mathcal{C}(I_{t-1}) + \mathcal{N}_t(\lambda),$$

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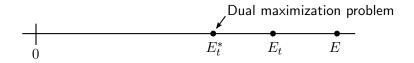
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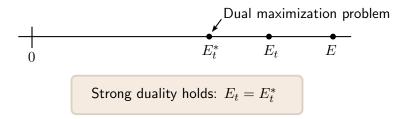
If an optimal solution λ of E_t satisfies $C(I_t) = C(I_{t-1}) + \mathcal{N}_t(\lambda)$, then $E_t = E_N = E$

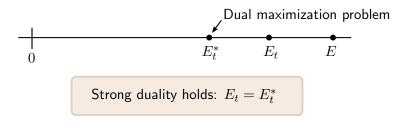




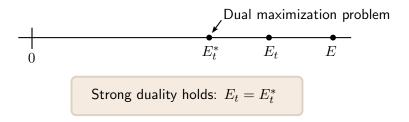




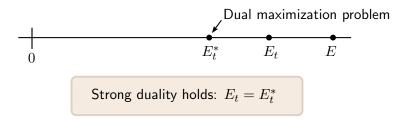




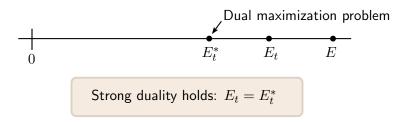
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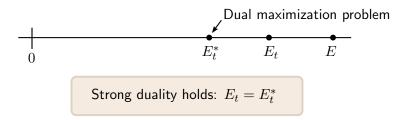


- ▶ In E_t^* we optimize over kernels $K \in C(I_t \times I_t)_{\succeq 0}$ ▶ Idea:
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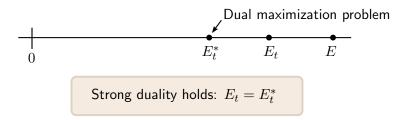
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Computations using the dual hierarchy



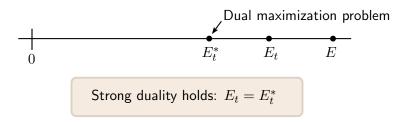
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- \blacktriangleright To do this we need a group Γ with an action on I_t
- In principle this can be the trivial group, but for symmetry reduction a bigger group is better

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- ▶ By an "averaging argument" we may assume $K \in C(I_t \times I_t)_{\geq 0}$ to be Γ -invariant: $K(\gamma J, \gamma J') = K(J, J')$ for all $\gamma \in \Gamma$ and $J, J' \in I_t$

► Fourier inversion formula:

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- The zonal matrices Z_π(x, y) are fixed matrices that depend on I_t and Γ (These matrices take the role of the exponential functions in the familiar Fourier transform)
- ► To construct the matrices Z_π(x, y) we need to "perform the harmonic analysis of I_t with respect to Γ"

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- We do this explicitly for V = S², Γ = O(3), and t = 2 (by using Clebsch–Gordan coefficients)
- ► We use this to lower bound E₂^{*} by maximization problems that have finitely many positive semidefinite matrix variables (but still infinitely many constraints)

These constraints are of the form

 $p(x_1, \ldots, x_4) \ge 0$ for $\{x_1, x_2, x_3, x_4\} \in I_{=4}$,

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- ▶ Now we have constraints of the form $q(u_1, \dots, u_l) \ge 0 \quad \text{for} \quad (u_1, \dots, u_l) \in \text{some semialgebraic set}$

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• This translates into interesting symmetries of the $q(u_1, \ldots, u_l)$ polynomials

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- This gives significant computational savings for our problems

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- This is the first time a four 4-bound has been computed for a continuous problem
- ► We show E₂^{*} is sharp for 5 particles on S² (up to solver precision), which suggests we can use E₂^{*} to derive a small proof of optimality for this problem



$$\sum_{1 \le i < j \le N} \frac{1}{\|x_i - x_j\|_2^s}$$

• The Riesz s-energy of a configuration $\{x_1, \ldots, x_N\} \subseteq S^2$:

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- It would be very interesting if E_2^* is sharp for all s
 - Lower bound that stays sharp throughout a phase transition
 - Local-to-global behaviour in confined geometries

Thank you!

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Image credits: Sphere packing: Grek L Elliptope: Philipp Rostalski Sodium Chloride: Ben Mills